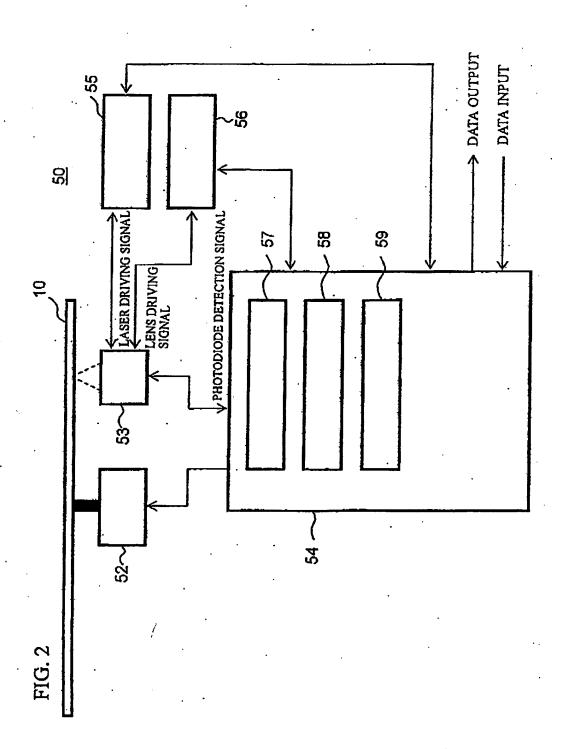
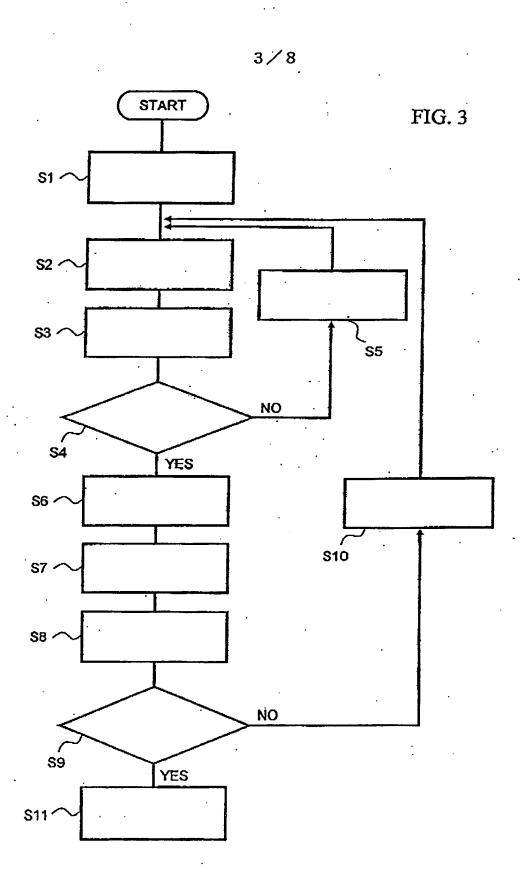
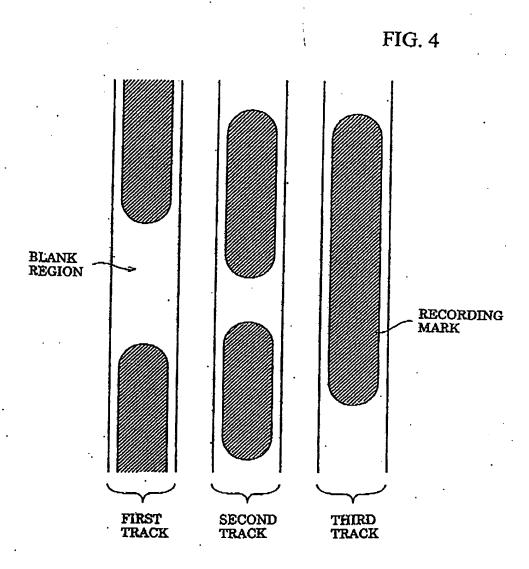


FIG.







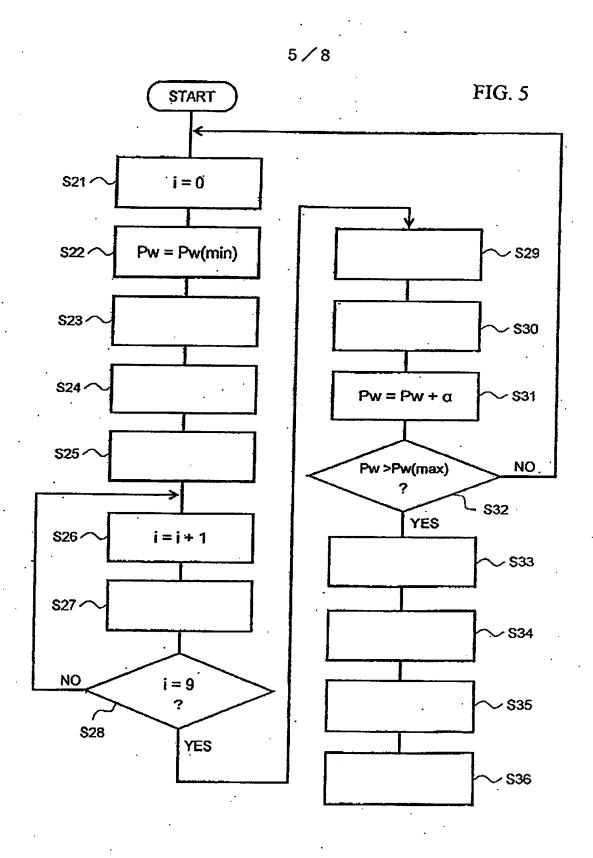


FIG. 6

•			•
	R1	R2	R3
Pw = Pw(min)	*****	*****	. ****
$Pw = Pw(min) + \alpha$	*****	*****	****
Pw = Pw(max)	*****	*****	*****

FIG. 7

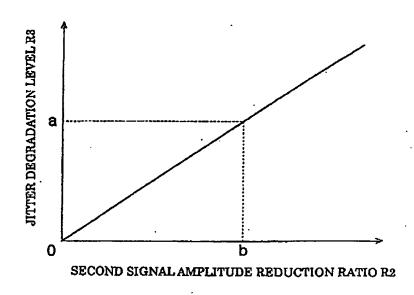
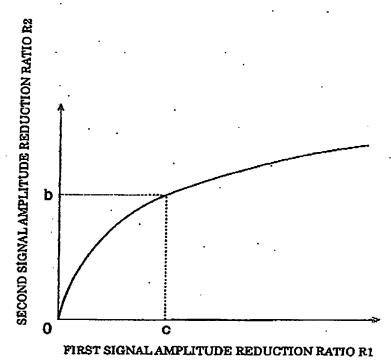


FIG. 8



·	
52·····SPINDLE MOTOR	
53HEAD	
54······CONTROLLER ·	
55······LASER DRIVING CIRCUIT	
56·····LENS DRIVING CIRCUIT	
57·····FOCUS SERVO CIRCUIT	•
58·····TRACKING SERVO CIRCUIT	
59······LASER CONTROL CIRCUIT	
S1······RECORDING TEST SIGNAL	
S2·····REPRODUCING TEST SIGNAL RECORDED ON	
SECOND TRACK	
S3MEASURING PREDETERMINED SIGNAL CHARACTERISTIC	S
S4······SIGNAL CHARACTERISTICS SATISFIES REFERENCE	
CONDITIONS?	
S5CHANGING RECORDING POWER PWAND RECORDING TES	T
SIGNAL	
S6······REPRODUCING TEST SIGNALS RECORDED ON SECOND	
TRACK AND THIRD TRACK	
S7MEASURING AMPLITUDE OF SIGNAL	
S8CALCULATING FIRST SIGNAL AMPLITUDE REDUCTION	
RATIO R1	
S9R1 IS EQUAL TO OR LOWER THAN RC?	
S10LOWERING RECORDING POWER PWAND RECORDING TEST	r .
SIGNAL	
S11DETERMINING OPTIMUM RECORDING POWER PW	
S23······RECORDING TEST SIGNAL	
S24REPRODUCING TEST SIGNALS RECORDED ON SECOND	
TRACK AND THIRD TRACK	
S25MEASURING JITTER AND AMPLITUDE OF SIGNAL	
S27······RECORDING TEST SIGNAL	
S29REPRODUCING TEST SIGNAL RECORDED ON SECOND TRAC	CE
S30MEASURING JITTER AND AMPLITUDE OF SIGNAL	
S33PRODUCING TABLE T	
S34······PRODUCING FIRST GRAPH	
S35PRODUCING SECOND GRAPH	
S36······DETERMINING RC	